

## TOT Program Course Syllabus

**Course Title: SPIKE PRIME Robotics – Python coding** 

**Prerequisites:** Basics of python and spike prime block-based environment

**Credit hours: 12** 

**Target audience:** Trainers and Teachers

## **Course Description:**

This is a TOT course meant for trainers who are interested in teaching and training the cutting-edge LEGO Robotics platform (SPIKE PRIME) which is the substitute for the EV3 platform. Trainees are going to step up their coding skills by getting specialized hands-on training based on python language to program spike robots. Starting from the design issues such as (building-pieces uses, movement systems, structuring robots' bases ...etc.), passing by the electronic components and their uses, coding skills, and not ending with a lot of implementations and practical applications.

The Content	Duration (hour)
	12
Subject 1: The work space & technical Jargon	
<ul> <li>Module</li> </ul>	
Routine	
• Coroutine	
<ul> <li>Coding mechanisms</li> </ul>	
Subject 2: Static import	
<ul> <li>Mechanisms</li> </ul>	
<ul> <li>Troubleshooting import issues</li> </ul>	
<ul> <li>Hierarchal structure of modules and methods</li> </ul>	
Subject 3: Utilizing The Hub	
<ul> <li>Modules, submodules, and methods in use</li> </ul>	
<ul> <li>Conditional statements in action</li> </ul>	
<ul> <li>Implementations</li> </ul>	
Subject 4: Straight movement	
<ul> <li>Modules, submodules, and methods in use</li> </ul>	
<ul> <li>Synchronous(p) commands vs Asynchronous(a) commands</li> </ul>	5
<ul> <li>Asynchronous commands – stategy1</li> </ul>	
<ul> <li>Asynchronous commands – stategy2</li> </ul>	
<ul> <li>Implementations</li> </ul>	
Subject 5: Rotation around the z-axis	
<ul> <li>Motion (gyro) sensor</li> </ul>	
<ul> <li>Configuration &amp; Yaw angle measurements</li> </ul>	
<ul> <li>Modules, submodules, and methods in use</li> </ul>	
<ul> <li>Constant Motor-speed technique</li> </ul>	
<ul> <li>Implementations</li> </ul>	
Subject 6: Sensors operation	
<ul> <li>The force sensor</li> </ul>	
<ul> <li>The distance sensor</li> </ul>	
The color sensor	
<ul> <li>Modules, submodules, and methods in use</li> </ul>	
<ul> <li>Implementations</li> </ul>	

## **Course Requirements:**

- 1. Laptop
- **2.** Spike Prime robotics core Kit